

Preparation of Abstracts for 2009 Asia-Pacific International Symposium on Aerospace Technology

First Author¹, and Second Author²

¹Department of...,University of...,City, Country
(E-mail address)

² Department of...,University of...,City, Country

Keywords: At least four keywords separated by commas

Abstract

The abstract must be written in English. It should present novel theory, experiment and numerical method or applications related to aerospace engineering and sciences concisely. It is limited in ONE PAGE. The author must upload your abstract in PDF FORMAT whose file name is APIxxx_abstract.pdf (xxx means your acceptance number) with your full paper electronically at the notified website address by September 4, 2009. The size of the PDF abstract should be kept within 1MB. Note that the APISAT 2009 web server cannot accept the electronic files other than PDF. A collection of the submitted abstracts will be distributed on site.

The paper size is 21.0cm×29.7cm. The margins are: top and bottom each 2.5cm, and left and right each 2cm. The column width is 8cm, and is separated by 1cm.

All fonts must be in Times New Roman font, and the font size of the title, authors' name, affiliation, abstract, and keywords are bold 11pt, 10pt, 9pt, 9pt, and 9pt, respectively. The top-level heading shall appear centered on the column with Times New Roman capital bold 10pt. Please use underline below the name of one author to specify the presenting author.

The figures are reduced to fit within the margins of each column. Symbols and legends are large enough to be readable. Tables and figures are numbered in the order they appear in the text.

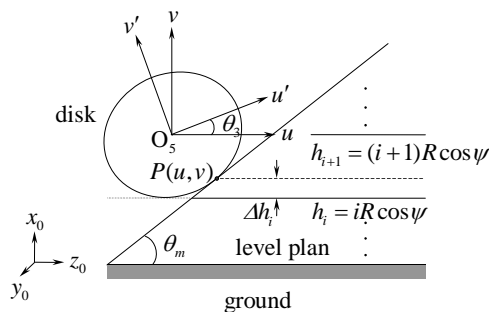


Fig. 1 The caption should be placed after the figure.

An Equation is centered on the column. The equation number should be Arabic numerals enclosed in parentheses on the right-hand margin. They should be cited in the text as, for example, Eq. (1), or Eqs. (1)-(3). Punctuate equations with commas or periods when they are part of a sentence. For example,

$$\dot{x} = Ax + Bu, \quad (1)$$

$$\hat{h}_n = \frac{1}{2\pi} \int_{-\pi}^{\pi} e^{-inx} h(x) dx \quad (2)$$

Please use the style "Equation", in which two tabs, center and right margin, are set.

REFERENCES

- [1] R. C. Baker and B. Charlie, "Nonlinear Unstable Systems," *International Journal of Control*, Vol. 23, No. 4, pp. 123-145, 1989.

- [2] G-D. Hong, "Linear Controllable Systems," *Nature*, Vol. 135, pp. 18-27, 1990.
- [3] K. S. Hong and C. S. Kim, "Linear stable systems," *IEEE Trans. on Automatic Control*, Vol. 33, No. 3, pp. 1234-1245, 1993.
- [4] Z. Shiler, S. Filter, and S. Dubowski, "Time optimal paths and acceleration lines of robotic manipulators," *Proc. of the 26th Conf. on Decision and Control*, pp. 98-99, 1987.
- [5] M. Young, *The Technical Writer's Handbook*, Mill Valley, Seoul, 1989.